Transformers and DC machines questions

1) In T-T connection, the ratio of actual capacity to the available capacity is

a. 1	
b. 0.928	
c. 1.928	
d. 0.5	
2) Whether the given autotransformer is step up or step down, its VA rating is always	
a. Greater than the two winding transformer	
b. Equal to the two winding transformer	
c. lesser than the two winding transformer	
d. cannot say	
3) In an autotransformer if the power transferred inductively is equal to the power conduthrough, then transformation ratio is given by	cted
a. 1	
b. 0.5	
c. 2	
d. 0	
4) In a 5 kV / 400V, 75 kVA single phase transformer, the current flowing in the primary w of transformer is 10A. what will be the current flowing in the secondary winding?	'indir
a. 100A	
b. 120A	
c. 125A	
d. 130A	

polarity and	rinding transformer is converted into an autotransformer by applying additive subtractive polarity which results in the secondary voltages of 1840 and 1810 voltinary and secondary voltages of transformer are
a. 1800V, 50\	<i>(</i>
b. 1810V, 40\	<i>(</i>
c. 1820V, 30\	<i>'</i>
d. 1825V, 15\	<u>'</u>
6) A star co	nnected three phase transformer is provided with tertiary delta connected winding
which allows	the flow of
a. Second ha	rmonic of exciting current
b. Third harm	onic of exciting current
c. Fifth harmo	nic of exciting current
d. Seventh ha	rmonic of exciting current
7) A 600 kV	A transformer has iron losses of 400 kW and copper losses of 500 kW. Its kVA
rating for ma	ximum efficiency is given by
a. 537 kVA	
b. 548 kVA	
c. 555 kVA	
d. 585 kVA	
_	transformer having transformation ratio equal to 0.6 is supplying a load of 8kw
•	if transferred from primary to secondary is given by
a. 3 kW	
b. 3.2 kW	
c. 3.4 kW d. 3.5 kW	

copper		
a. Increases		
b. Decreases		
c. Remains same		
d. None of these		
10) A 500 kVA sin	le phase transformer has 90% efficiency at both half load and full load at	_
unity power factor	Then iron losses will be	
a. 12.55 KW		
b. 13.55 kW		
c. 16.55 kW		
-	00 / 220 volts transformer iron and copper losses are 300 and 400 watts	
11) ln a 20 kVA, 2	00 / 220 volts transformer iron and copper losses are 300 and 400 watts ciency at half load and unity power factor is	
11) In a 20 kVA, 2 respectively. Its ef a. 95.11%		
11) In a 20 kVA, 2 respectively. Its ef a. 95.11% b. 96.15%		
11) In a 20 kVA, 2 respectively. Its ef a. 95.11% b. 96.15% c. 97.77% d. 98%		ŀ
11) In a 20 kVA, 2 respectively. Its ef a. 95.11% b. 96.15% c. 97.77% d. 98%	ciency at half load and unity power factor is nce is to be transferred from primary to secondary side of transformer wit	
11) In a 20 kVA, 2 respectively. Its ef a. 95.11% b. 96.15% c. 97.77% d. 98%	ciency at half load and unity power factor is nce is to be transferred from primary to secondary side of transformer wit	: r
11) In a 20 kVA, 2 respectively. Its ef a. 95.11% b. 96.15% c. 97.77% d. 98% 12) When a resist the turns ratio as k	ciency at half load and unity power factor is nce is to be transferred from primary to secondary side of transformer wit	:r
11) In a 20 kVA, 2 respectively. Its ef a. 95.11% b. 96.15% c. 97.77% d. 98% 12) When a resist the turns ratio as k a. Multiplied by k A 2	ciency at half load and unity power factor is nce is to be transferred from primary to secondary side of transformer wit	: !

9) In a step down autotransformer, if the transformation ratio increases then the saving of

	ormer. Then the saving of copper is given by
a. K W _{tw}	
b. W _{tw} / K	
c. W _{tw} / K ∧ 2	
d. K ² W _{tw}	
14) The most commonly use	d connections for power systems as a step - up and step - down
transformers are	
a. Star - delta, star - star	
b. Delta - star, star - delta	
c. Star - star, delta - delta	
d. Star - delta, delta - star	
	Iging. The magnetizing current (I_m) and core loss (P_c) is equal to
a. 3.919A, 184Wb. 1.84A, 391.9Wc. 39.19A, 184Wd. 3A, 180W	
b. 1.84A, 391.9W c. 39.19A, 184W d. 3A, 180W	arator used for the protection of three phase transformers has

13) If K is the transformation ratio of step up autotransformer and W_{tw} is the total weight of

17)) For a single phase no load transformer, whi	ich among the following losses will be
min	nimum?	

- a. hysteresis losses
- b. eddy current losses
- c. copper losses
- d. mechanical losses

18) In double delta transformation, a double delta refers to the case where there are two delta transformations in

- a. Parallel
- **b.** Series
- c. Both series and parallel
- d. Neither series nor parallel

19) Most familiar application of zig - zag transformer is as

- a. Ground reference on an ungrounded system
- b. Converting single phase to two phase
- c. Reducing harmonics
- d. All of these

20) In a single phase, full wave bridge circuit and in three phase, delta full wave bridge circuit, the ripple voltage frequency is always

- **a.** Twice the line frequency, six times the line frequency
- **b.** Both will be twice the line frequency
- c. Both will be six times the lines frequency
- d. None of these

b. 60 degree	
c. 90 degree	
d. 120 degree	
22) Scott co	nnection is used for the conversion of
a. Single phas	se to three phase
b. Three phas	se to single phase
c. Single phas	se to two phase
d. All of these	
a. 50%, 86.6% b. 50%, 50% c. 86.6%, 86.6%	6%
_	ank of two single phase transformers connected in V - V fashion supplying a see phase load with Cosφ as power factor. The power factor of the two transforme
balanced three	ee phase load with Cosφ as power factor. The power factor of the two transformer
balanced three is given by a. Cosφ, Cos	ee phase load with Cos ϕ as power factor. The power factor of the two transformer ϕ
balanced thre	ee phase load with Cos ϕ as power factor. The power factor of the two transformed ϕ (30+ ϕ)

21) In Scott connection, the voltage across the teaser leads the mains by

power factor is
a. 57.7% of the balanced load power factor
b. 66.7% of the balanced load power factor
c. 86.6% of the balanced load power factor
d. None of theses
26) Consider three transformers connected in delta-delta fashion and supplying their rated load. Now if one of the transformer is removed then each of the remaining two transformer is overloaded. The overload on each transformer is given as
a. 1
b. 1.232
c. 1.732
d. 1.872
27) The load carried by V - V connection is
a. 47.7% of the original load
b. 57.7% of the original load
c. 67.7% of the original load
d. 87.7% of the original load
28) In case of delta-star connection of three phase transformer, secondary line voltage with respect of primary line voltage is at
a. 0 degree
b. 30 degree leading
c. 30 degree lagging
d. 60 degree lagging

25) The average power factor at which V-V bank is operating is less than that with the load. The

a. Star - star connection	
b. Delta - delta connection	
c. V connection	
d. All of these	
30) If K is the transformation ratio, then the secondary phase voltage of three phase transformer will be	delta-delta connecte
a. 1 / K times of the primary phase voltage	
b. Equal to the primary phase voltage	
c. 1 / K ∧ 2 times of the primary phase voltage	
d. K times the primary phase voltage	
 a. Remains same b. Increases c. Decreases d. None of these 	
32) With the increase in temperature, the speed of series and shunt motor	or will
a. Increase, decrease	
b. Decrease, increase	
c. Increase, increase	
d. Decrease, decrease	

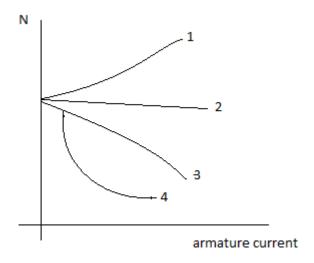
29) For large low voltage transformers, the most commonly used connections are

c. Voltage control method
d. All of these
34) Due to armature reaction magnetic neutral axis gets shifted by some angle. In case o
motors the brushes are shifted
a. Forwards same as the direction of rotation
b. Backwards opposite to the direction of rotation
c. Either (a) or (b)
d. Does not get shifted
35) In electric traction, which type of motor is generally used?
a. Shunt motor
b. Series motor
c. Cumulative compound motor
d. Differential compound motor
36) In a differential compound d.c. motor, with increase in load, speed
a. Increases
b. Decreases
c. Remains same
d. None of these
37) The speed current characteristics are shown in the given figure. Identify the differen
curves.

33) Speed of d.c. shunt motors are controlled by

a. Flux control method

b. Rheostatic control method



- a. 1 series, 2 shunt, 3 cumulative compound, 4 differential compound
- **b.** 1 cumulative compound, 2 differential compound, 3 series, 4 shunt
- c. 1 cumulative compound, 2 differential compound, 3 shunt, 4 series
- d. 1 differential compound, 2 shunt, 3 cumulative compound 4 series
- 38) Cumulative compound motor is capable of developing large amount of torque at low speeds just like series motor. Can cumulative compound motor be run on light load or no load
- a. Yes
- **b.** No

- 39) A long shunt compound motor and a short shunt compound motor can be
- a. Cumulative type, differential type
- **b.** Differential type, cumulative type
- c. Both can be either cumulative or differential type
- d. None of these
- 40) D.C. series motors are used in electric traction. What happens to the speed and current of

d.c motor if there is sudden slight drop in the mains voltage?

- a. Speed decreases and current also decreases
- b. Speed decreases and current increases
- c. Speed increases and current decreases
- d. Speed decreases and current remains same

41) If a d.c. series motor is started on very light load or on no load then

- a. It will run at dangerously high speed which may damage the motor mechanically
- b. It will run at very low speed
- c. Load does not effect the speed of d.c. series motor
- d. None of these

42) The speed armature current characteristics of a d.c. series motor is

- a. Rectangular hyperbola
- **b.** Linear
- c. Parabolic
- d. Parabolic till saturation and then linear

43) The speed of a d.c. series motor is

- a. Directly proportional to the both armature current and torque developed
- **b.** Inversely proportional to the armature current and square root of torque developed
- c. Directly proportional to the square of the armature current and square root of torque developed
- d. Inversely proportional to the square of the armature current and square of torque developed

44) The starting torque developed in the d.c. series motor and in d.c. shunt motor is

- a. High, low
- **b.** High, moderate
- c. Moderate, low

d. Moderate, high	
armature resistance and the fie	motor has a wave wound armature with 180 conductors. The eld winding resistance are 0.10 ohm and 0.2 ohm respectively. If ent at 0.015 Wb flux per pole, then the speed under this condition
is	
a. 2533.3 rpm	
b. 2644.4 rpm	
c. 2756.9 rpm	
d. 2987.6 rpm	
, ,	ne current drawn from by a d.c. series motor is increased from 1 the torque expressed as percentage of initial torque will be
a. 22 %	
b. 33%	
c. 44%	
d. 56.78%	
47) For d.c. series motor, if I_a	is the armature current then the torque developed is
a. α l _a	
b. αI_a^2	
c. $\alpha (1/I_a^2)$	
d. α (1 / I _a)	
48) A 4 pole, 220 V, 10 H.P, d.o developed useful torque is	c. shunt motor is rotating at a speed of 320 rpm. Then the
a. 210.647 N-m	
b. 215.547 N-m	
c. 219.484 N-m	
d. None of these	

49)	For a constant torque load, if the armature resistance of shunt motor is doubled (keepin	ıg
the	shunt field constant) then the armature current will	

- a. Double
- b. Get halved
- c. Remain same
- d. None of these

50) The torque developed in d.c. shunt motor is

- a. Directly proportional to the armature current
- b. Directly proportional to the square of the armature current
- c. Inversely proportional to the armature current
- d. Inversely proportional to the square of armature current

51) D.C. shunt motor is also called as

- a. Constant flux motor
- **b.** Constant voltage motor
- c. Variable voltage motor
- **d.** Constant current motor

52) Keeping the field excitation constant, the constant of proportionality between back emf an armature speed of d.c. motor is

- a. Twice of the proportionality constant between developed torque and armature current
- b. Half of the proportionality constant between developed torque and armature current
- c. Same as that of proportionality constant between developed torque and armature current
- d. None of these

53) If the back emf of a d.c. motor is doubled and flux is halved (keeping other parameters

	nai speed
b. Square of the orig	inal speed
c. Four times of the o	original speed
d. Half of the original	speed
54) As the load on	d.c. motor increases, the current drawn by motor
a. Increases	
b. Decreases	
c. Remains same	
d. None of these	
•	speed of d.c. motor is 1350 rpm and full load speed is 1150 rpm, then its
voltage regulation i	
voltage regulation i a. 11.56 %	
voltage regulation i a. 11.56 % b. 15.36 %	
voltage regulation i a. 11.56 %	
voltage regulation i a. 11.56 % b. 15.36 % c. 17.39 % d. 19.39 %	
voltage regulation i a. 11.56 % b. 15.36 % c. 17.39 % d. 19.39 % 56) A 4 pole, lap w the flux per pole is	ound d.c. motor drawing an armature current of 20 A has 360 conductors
voltage regulation i a. 11.56 % b. 15.36 % c. 17.39 % d. 19.39 % 56) A 4 pole, lap w the flux per pole is a. 10.23 N-m	ound d.c. motor drawing an armature current of 20 A has 360 conductors
voltage regulation i a. 11.56 % b. 15.36 % c. 17.39 % d. 19.39 %	ound d.c. motor drawing an armature current of 20 A has 360 conductors

57) If E_b is the back emf of d.c. motor and V is the terminal voltage, then the condition for

constant) then its speed will become

maximum power is

- **a.** $E_b = V$
- **b.** $E_b = 2V$
- **c.** $E_b = (V/2)$
- **d.** $E_b = V \wedge 2$
- 58) If the flux is increased by 50% and speed is reduced by 50% of a d.c. motor (keeping the other parameters constant), then its back emf will become
- a. 50 % of the original back emf
- b. 0.75 % of the original back emf
- c. 100 % of the original back emf
- d. 150 % of the original back emf
- 59) A 220 V, d.c. motor draws an armature current of 20 A. Its armature resistance is 0.6 ohm. Then the induced emf in the motor will be
- **a.** 195 V
- **b.** 202 V
- **c.** 208 V
- **d.** 215 V
- 60) In a practical motor, to reverse the direction of rotation
- a. Reverse the direction of main field produced by the field winding
- b. Reverse the direction of current passing through the armature is reversed
- c. Either (a) or (b)
- d. None of these