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Presentation On

Solving Statically Determinate Structures

Static Equilibrium

A system of particles is in static equilibrium when all the particles of the system are at rest and the total force on each particle is permanently zero.

Statically Determinate

Amember or structure that can be analyzed and the reactions and forces determined from the equations of equilibrium.

Statically Indeterminate

Amember or structure that cannot be analyzed by the equations of statics. It contains unknowns in excess of the number of equilibrium equations available.

Determinacy

- r = 3n, statically determinate r > 3n, statically indeterminate where,
- \mathbf{n} = the total parts of structure members
- \mathbf{r} = the total number of unknown reactive forces and moment components



The excess members or reactions of an indeterminate structures are called redundants. Redundant forces are chosen so that the structure is stable and statically determinate when they are removed.

How do we make an indeterminate structure statically determinate? If there is two degrees of indeterminacy, we have to remove two reactive forces, remove three for three degrees and so forth.

Byremoving excess supports.

By introducing hinges.

What are the advantages of statically indeterminate structures over determinate structures?

There are several advantages in designing indeterminate structures. These include the design of lighter and more rigid structures. With added redundancy in the structural system, there is an increase in the overall factor of safety.



Structural Design and Inspection-Deflection and Slope of Beams

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Suggested Readings

Reference 1 Chapter 16



Objective

 To obtain slope and deflection of beam and frame structures using slope-deflection method

Introduction

 Structural analysis method for beams and frames introduced in 1914 by George A. Maney

 This method was later replaced by moment distribution method which is more advanced and useful (students are encouraged) to study this separately

- Sign convention:
 - Moments, slopes, displacements, shear are all in positive direction as shown
- Axial forces are ignored



$$EI\frac{d^2v}{dx^2} = M_{AB} + S_{AB} \rightarrow$$

$$\begin{cases} EI \frac{dv}{dx} = M_{AB} x + S_{AB} \frac{x^2}{2} + C_1 \\ EIv = M_{AB} \frac{x^2}{2} + S_{AB} \frac{x^3}{6} + C_1 x + C_2 \end{cases} \rightarrow$$

$$@ x = 0 \Rightarrow \frac{dv}{dx} = \theta_A v = v_A \rightarrow$$

$$@ x = L \Longrightarrow \frac{dv}{dx} = \theta_B v = v_B \Longrightarrow$$

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Solving for M_{AB} and S_{AB}

$$M_{AB} = -\frac{2EI}{L} \left[2\theta_A + \theta_B + \frac{3}{L} (v_A - v_B) \right] \qquad S_{AB} = \frac{2EI}{L} \left[\theta_A + 2\theta_B + \frac{3}{L} (v_B - v_B) \right] \qquad S_{B\overline{A}} = \frac{2EI}{L} \left[\theta_A + 2\theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + 2\theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + 2\theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + 2\theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + 2\theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + 2\theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + 2\theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + 2\theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + 2\theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + 2\theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + 2\theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + 2\theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + 2\theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + 2\theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + 2\theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + 2\theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + \theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + \theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + \theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + \theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + \theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + \theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + \theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + \theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + \theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + \theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + \theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + \theta_B + \frac{3}{L} \left[\theta_A + \theta_B + \frac{3}{L} (v_B - v_B) \right] = \frac{3}{L} \left[\theta_A + \theta_B + \frac{3}{L} \left[\theta_A + \theta_B$$

$$T_{AB} = \frac{6EI}{L^{2}} \left[\theta + \theta + \theta^{2} \left(\psi - \psi_{A} \right)^{T} \right]_{B}$$

$$T_{B\overline{A}} = \frac{6EI}{L^{2}} \left[\theta_{A} + \theta + \theta^{2} \left(\psi - \psi_{A} \right)^{T} \right]_{B}$$

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 Last 4 equations obtained in previous slide are called slope-deflection equations

They establish force-displacement relationship

 This method can find exact solution to indeterminate structures

 The beam we considered so far did not have any external loading from A to B



In the presence of mid-span loading (common engineering problems) the equations become:

$$M_{AB} = -\frac{2EI}{L} \left[2\theta_{A} + \theta_{B} + \frac{3}{L} (v_{A} v_{A} v_{B}) + M \right] \left[\left(\begin{array}{c} F \\ AB \end{array} \right) \right] \left[\left(\begin{array}{c} F \\ AB \end{array} \right) \right] \left[\left(\begin{array}{c} F \\ AB \end{array} \right) \right] \left[\left(\begin{array}{c} F \\ AB \end{array} \right) \right] \left[\left(\begin{array}{c} F \\ AB \end{array} \right) \right] \left[\left(\begin{array}{c} F \\ AB \end{array} \right) \right] \left[\left(\begin{array}{c} F \\ AB \end{array} \right) \right] \left[\left(\begin{array}{c} F \\ AB \end{array} \right) \right] \left[\left(\begin{array}{c} F \\ AB \end{array} \right) \right] \left[\left(\begin{array}{c} F \\ AB \end{array} \right) \right] \left[\left(\begin{array}{c} F \\ AB \end{array} \right) \right] \left[\left(\begin{array}{c} F \\ AB \end{array} \right) \right] \left[\left(\begin{array}{c} F \\ AB \end{array} \right) \right] \left[\left(\begin{array}{c} F \\ AB \end{array} \right) \right] \left[\left(\begin{array}{c} F \\ AB \end{array} \right) \left[\left(\begin{array}{c} F \\ AB \end{array} \right) \right] \left[\left(\begin{array}{c} F \\ AB \end{array} \right) \right] \left[\left(\begin{array}{c} F \\ AB \end{array} \right) \left[\left(\begin{array}{c} F$$

Fixed End Moment/Shear

- M_{AB}F, M_{BA}F are fixed end moments at nodes A and B, respectively.
 - Moments at two ends of beam when beam is clamped at both ends under external loading (see next slides)
- S_{AB}F, S_{BA}F are fixed end shears at nodes A and B, respectively.
 - Shears at two ends of beam when beam is clamped at both ends under external loading (see next slides)

Fixed End Moment/Shear



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Fixed End Moment/Shear



Example

• Find support reactions.



• This beam has 2 degrees of indeterminacy



1- Assume all beams are fixed & calculate FEM

2- Establish Slope-Deflection equations 3- Enforce boundary conditions & equilibrium conditions at joints

4- Solve simultaneous equations to get slopes/deflections



$$M_{AB} = -\frac{2EI}{1.0}(2\theta_{A} + \theta_{B}) - 0.75$$

$$M_{BA} = -\frac{2EI}{1.0}(2\theta_{B} + \theta_{A}) + 0.75$$

$$M_{BC} = -\frac{2EI}{1.0}(2\theta_{B} + \theta_{C}) - 1.25$$

$$M_{CB} = -\frac{2EI}{1.0}(2\theta_{C} + \theta_{B}) + 1.25$$

$$M_{CD} = -\frac{2EI}{1.0}(2\theta_{C} + \theta_{D}) - 1.0$$

$$M_{DC} = -\frac{2EI}{1.0}(2\theta_{D} + \theta_{C}) + 1.0$$

$$M_{ij} = -\frac{2EI}{L}\left[2\theta_{i} + \theta_{j} + \left(\frac{3}{L} v_{i} - v_{j}\right)\right] M_{ij}^{F}$$

$$M_{ij} = -\frac{2EI}{L}\left[\frac{2\theta_{i} + \theta_{j} + \left(\frac{3}{L} v_{i} - v_{j}\right)\right]}{L}\left[\frac{\theta_{i} + 2\theta_{j} + \left(\frac{3}{L} v_{i} - v_{j}\right)\right]}{L}\left[\frac{\theta_{i} - v_{i}}{L}\right]$$

 $v_{i}=0$ and $v_{j}=0$ for all cases

• Equilibrium moments at the joints



 Substitution into slope deflection equations gives 4 equations and 4 unknown slopes.

 $4EI\theta_{A} + 2EI\theta_{B} + 0.75 = 0$ $2EI\theta_{A} + 8EI\theta_{B} + 2EI\theta_{C} + 0.5 = 0$ $2EI\theta_{B} + 8EI\theta_{C} + 2EI\theta_{D} - 0.25 = 0$ $4EI\theta_{D} + 2EI\theta_{C} - 1.0 = 0$

By simultaneously solving the equations

 $EI\theta_{A} = -0.183$ $EI\theta_{B} = -0.008$ $EI\theta_{C} = -0.033$ $EI\theta_{D} = +0.267$

• Simply operation of substitution:

$$\begin{split} M_{\rm AB} &= -\frac{2EI}{1.0}(2\theta_{\rm A} + \theta_{\rm B}) - 0.75 & EI\theta_{\rm A} = -0.183 & M_{\rm AB} = 0 \\ M_{\rm BA} &= -\frac{2EI}{1.0}(2\theta_{\rm B} + \theta_{\rm A}) + 0.75 & M_{\rm BA} = 1.15 \\ M_{\rm BC} &= -\frac{2EI}{1.0}(2\theta_{\rm B} + \theta_{\rm C}) - 1.25 & EI\theta_{\rm B} = -0.008 & M_{\rm BC} = -1.15 \\ M_{\rm CB} &= -\frac{2EI}{1.0}(2\theta_{\rm C} + \theta_{\rm B}) + 1.25 & M_{\rm CB} = 1.4 \\ M_{\rm CD} &= -\frac{2EI}{1.0}(2\theta_{\rm C} + \theta_{\rm D}) - 1.0 & M_{\rm CD} = -1.4 \\ M_{\rm DC} &= -\frac{2EI}{1.0}(2\theta_{\rm D} + \theta_{\rm C}) + 1.0 & EI\theta_{\rm D} = +0.267 & M_{\rm DC} = 0 \\ \end{split}$$

Now support reactions can easily be calculated as







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Example 2

 Obtain moment reaction at the clamped support *B* for 6m long beam if support *A* settles down by 5mm. *El*=17×10¹² Nmm²



Solution

$$\int \frac{1}{M_{ij}} = -\frac{2EI}{L} \left[2\theta_i + \theta_j + \left(\frac{3}{L} v_i - v_j\right) \right] M_{ij}^F \right] M_{ji}^F = -\frac{2EI}{L} \left[(\theta_i + 2\theta_j + \left(\frac{3}{L} - v_i\right) + M_{ji}^F \right]) M_{ji}^F = -\frac{2EI}{L} \left[(\theta_i + 2\theta_j + \left(\frac{3}{L} - v_i\right) + M_{ji}^F \right]) M_{AB}^F \right] M_{AB}^F = -\frac{2EI}{L} \left[2\theta_A + \theta_B + \frac{3}{L} (v_A - v_B) \right] + M_{AB}^F \right]$$

$$\int M_{AB} = 0 = -\frac{2EI}{L} \left[2\theta_A + 0 + \frac{3}{L} \left(0.05 - 0 \right) \right] \frac{4000 \times L^2}{12} + \frac{1}{12} \int \frac{1}{2} \left(\frac{4000}{24EI} L^3 + \frac{0.0015}{L} \right) / (2 - 9) - 33 \times 10^{-4} had$$

Solution

$$\int \frac{d}{dkN/m} + \frac{$$
Case study



3



Case study

Rotation and displace ment can be obtained from the SFN

Wire in composite beam

Case study



• Determine the support reactions in the beam shown below.



Ans. $R_A = 3.5 \text{ kN}$ $R_B = 9.0 \text{ kN}$ $R_C = 3.5 \text{ kN}$ $M_A = 7 \text{ kN} \text{ m}$ (hogging) $M_C = -19 \text{ kN} \text{ m}$ (hogging).

 Calculate the support reactions in the beam shown below.



Ans. $R_A = 3.3 \text{ kN}$ $R_B = 14.7 \text{ kN}$ $R_C = 4.0 \text{ kN}$ $M_A = 2.2 \text{ kN} \text{ m}$ (hogging).

• Determine the end moments in the members of the portal frame shown. The second moment of area of the vertical members is 2.51 while that of the horizontal members is I.



 Analyze two span continuous beam ABC by slope deflection method. Then draw Bending moment & Shear force diagram. Take El constant.



Outline of the presentation

- Introduction to moment distribution method.
- Important terms.
- Sign conventions.
- Fixed end moments (FEM)
- Examples;
- (A) example of simply supported beam
- (B) example of fixed supported beam with sinking of support.



The moment distribution method was first introduced by Prof. Hardy Cross of Illinois University in 1930.

This method provides a convinient means of analysing statically indeterminate beams and rigid frames.

It is used when number of reduntants are large and when other method becomes very tedious. 1. Stiffness

Important terms

The moment required to produce a unit rotation (slope) at a simply supported end of a member is called Stiffness. It is denoted by 'K'.

- A) Stiffness when both ends are hinged.
- B) Stiffness when both ends are fixed.

A) Beam hinged at both ends:



$$\frac{M_{AB}}{\theta_{AB}} = \frac{3EI}{L}$$

i.e., the moment required at A to induce a unit rotation at A is $\frac{3EL}{L}$ (when the far end B is free to rotate)

This moment, i.e., moment required to induce a unit rotation, is called stiffness (denoted by k).

Cont..

B) Beam hinged at near end and fixed at far end:



i.e., the moment required at A to induce a unit rotation at A is (when the far end B is fixed against rotation)

Cont.. Carry over factor (C.O.F):

A moment applied at the near end induces at a fixed far end a moment equal to half its magnitude, in the same direction.

Half of moment applied at the near end is carried over to the fixed far end.

Carry over factor is 1/2.

Distribution factor (D.F.)

- The factor by which the applied moment is distributed to the member is known as the distribution factor.
 - - far-end pined (DF = 1)

• Figure:

- far-end fixed (DF = 0)

Several members meeting at a joint

$$M_1 = \frac{3E_1I_1}{L_1}\theta = k_1\theta$$

$$M_2 = \frac{4E_2I_2}{L_2}\theta = k_2\theta$$

$$M_3 = \frac{3E_3I_3}{L_3}\theta = k_3\theta$$

$$M_{4} = \frac{4E_{4}I_{4}}{L_{4}}\theta = k_{4}\theta$$

 $M_1: M_2: M_3: M_4:: k_1: k_2: k_3: k_4$

$$M_{1} = \frac{k_{1}}{k_{1} + k_{2} + k_{3} + k_{4}}M = \frac{k_{1}}{\Sigma k}M$$

$$M_{i} = \frac{k_{i}}{\Sigma k}M$$

A moment applied at a joint, where several members meet, will be distributed amongst the members in proportion to their stiffness.

$$M_{i} = \underbrace{\begin{matrix} k_{i} \\ \Sigma k \end{matrix}}_{\text{distribution factor}}$$

Sign Conventions

A)Support moments : clockwise moment = +ve anticlockwise moment = -ve

B)Rotation (slope):

clockwise moment = +ve

anticlockwise moment =-ve



C) Sinking (settlement)

• The settlement will be taken as +ve, if it rotates the beam as a whole in clockwise direction.

The settlement will be taken as -ve, if it rotates the beam as a whole in anti-clockwise direction.



- The fixed end moments for the various load cases is as shown in figure;
- . a) for centric loading;



Cont..

b) for eccentric loading, udl,rotation,sinking of supports & uvl







• Fixed end moment for sinking of supports:







Fixed end moments

$$-FEM_{AB} = FEM_{BA} = \frac{wl^2}{12} + \frac{Pl}{8} = \frac{20 \times 6^2}{12} + \frac{40 \times 6}{8} = 60 + 30 = 90 \, kNm$$
$$-FEM_{BC} = FEM_{CB} = \frac{wl^2}{12} + \frac{Pl}{8} = \frac{20 \times 6^2}{12} + \frac{60 \times 6}{8} = 60 + 45 = 105 \, kNm$$
$$-FEM_{CD} = FEM_{DC} = \frac{Pl}{8} = \frac{80 \times 6}{8} = 60 \, kNm$$



Cont

А	В		C		D	
	0.429	0.571	0.571	0.429		Distribution factors
-90	+90	-105	+105	-60	+60	Fixed End Moments
+90	+45			-30	-60	Release A& D, and carry over
0	+135	-105	+105	-90	0	Initial moments
	-12.87	-17.13	-8.565	-6.435		Distribution
8	99 91	-4.283	-8.565			Carry over
~	+1.837	+2.445	4.89	3.674		Distribution
		+2.445	1.223			Carry over
	-1.049	-1.396	- <mark>0.6</mark> 98	-0.524		Distribution
0	+122.92	-122.92	+93.29	- 93.29	0	Final Moments



$$M_{f} AB = -\frac{Wl}{8} = -\frac{15 \times 4}{8} = -7.5 \text{ kN.m}$$

$$M_{f} BA = +\frac{Wl}{8} = 7.5 \text{ kN.m}$$

$$M_{f} BC = -\frac{Wl^{2}}{12} = -\frac{16 \times 3^{2}}{12} = -12 \text{ kN.m}$$

$$M_{f} CB = +\frac{Wl^{2}}{12} = 12 \text{ kN.m}$$

$$M_{f} CD = -\frac{Wab^{2}}{l^{2}} = -\frac{25 \times 1 \times 2^{2}}{3^{2}} = -11.11 \text{ kN.m}$$

$$M_{f} DC = +\frac{Wba^{2}}{l^{2}} = \frac{25 \times 2 \times 1^{2}}{3^{2}} = 5.55 \text{ kN.m}$$

(b) Distribution Factors (D.F.) :

Sr.No.	Joint	Member	k	Σk	D.F. = $\frac{\mathbf{k}}{\Sigma \mathbf{k}}$
1.	в	ВА	$\frac{4 \text{ EI}}{4} = 1.0 \text{ EI}$		0.27
- Contract		ВС	$\frac{4 \mathrm{E}(2\mathrm{I})}{3} = 2.67 \mathrm{EI}$	3.67 EI	0.73
2.	C	СВ	$\frac{4 \text{ E} (21)}{3} = 2.67 \text{ EI}$	to and the	0.67
	and the second	CD	$\frac{4 \text{ EI}}{3} = 1.33 \text{ EI}$	4.0 EI	0.33
3.	A	Contration 10	-		
4.	D		COLUMN AND AND AND AND AND AND AND AND AND AN	and the second s	0

) Mo	ment Dist	ribution	(M.D.) :				A MALWERSON AND AND AND AND AND AND AND AND AND AN
A		В		C			and and a set
	0	0.27	0.73	0.67	0.33	0	DE
Sum	-7.5	7.5	-12	12	-11.11	5.55	F.E.M.
	0	1.21	3.28	-0.59	-0.30	_0	Balance
	0.60	-0	-0.30	1.64	0	-0.15	C.O.
	0_	0.08	0.22	-1.10	-0.54	0	Balance
	0.04	~ 0	-0.55	-0.11	0	-0.27	c.o.
	0	0.15	0.40	-0.07	-0.04	0	Balance
	0.075	~0	-0.035	0.20	0	-0.03	2 C.O.
	0	0.009	0.026	-0.13	-0.07	0	Balance
	-6.79	8.95	-8.95	12.06	-12.06	5.1	I Final momen
	1					1 -	Lalonci

 $M_{AB} = -6.79$ kN.m.

 $M_{BA} = 8.95 \text{ kN.m.} M_{BC} = -8.95 \text{ kN.m}$ $M_{CB} = 12.06 \text{ kN.m.} M_{CD} = -12.06 \text{ kN.m}$

 $M_{DC} = 5.11 \text{ kN.m}$

(d) B.M. diagram :

0

Simply supported moments.

Span AB. M =
$$\frac{Wl}{4} = \frac{15 \times 4}{4} = 15$$
 kN.m
Span BC. M = $\frac{Wl^2}{8} = \frac{16 \times 3^2}{8} = 18$ kN.m
Span CD. M = $\frac{Wab}{l} = \frac{25 \times 1 \times 2}{3} = 16.67$ kN.m

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Structural .



Example

Support B settles by 10 mm.

 $E = 200GPa, \quad I = 50 \times 10^6 mm^4$



$$\frac{Pl}{8} = \frac{20 \times 8}{8} = 20 \, kNm \qquad \qquad \frac{wl^2}{12} = \frac{3 \times 8^2}{12} = 16 \, kNm$$

$$FEM_{AB} = \frac{-Pl}{8} - \frac{6EI\delta}{L^2}$$

$$= -20 - \frac{6 \times 2 \times 200 \times 10^6 \times 50 \times 10^6 \times 10^{-12} \times 10 \times 10^{-3}}{8^2}$$

$$= -20 - 18.75 = -38.75 \, kNm$$

$$FEM_{BA} = \frac{Pl}{8} - \frac{6EI\delta}{L^2}$$

$$= 20 - \frac{6 \times 2 \times 200 \times 10^6 \times 50 \times 10^6 \times 10^{-12} \times 10 \times 10^{-3}}{8^2}$$

$$= 20 - 18.75 = 1.25 \, kNm_{\odot}$$

$$FEM_{BC} = \frac{-wl^2}{12} + \frac{6EI\delta}{L^2}$$

=16+

$= -16 + \frac{6 \times 3 \times 200 \times 10^{6} \times 50 \times 10^{6} \times 10^{-12} \times 10 \times 10^{-3}}{8^{2}}$

= -16 + 28.125 = 12.125 kNm

$$FEM_{CB} = \frac{wl^2}{12} + \frac{6EI\delta}{L^2}$$

16 + 6×3×200×10⁶ × 50×10⁶ × 10⁻¹² × 10×10⁻³

8²

=16+28.125=44.125 kNm

A		В	C		
1	0.333	0.667	0		
-38.75	+1.25	12.125	44.125	Fixed End Moments	
38.75	19.375			carry over	
0.0	20.625	12.125	44.125	Initial Moments	
	-10.906	-21.844	0	Distribution	
		2	-10.922	Carry over	
				Distribution	
0.0	+ 9.719	-9.719	+33.203	Final Moments	



Structural Analysis -II

Approximate Methods

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Modulo

Approximate Methods of Analysis of Multi-storey Frames

- Analysis for vertical loads Substitute frames-Loading conditions for maximum positive and negative bending moments in beams and maximum bending moment in columns
- Analysis for lateral loads Portal method–Cantilever method– Factor method.
Why approximate

- Rapid check on computer aided analysis
- Preliminary dimensioning before exact analysis

Advantage • Faste

Disadvantage • Results are

•Approximate methods are particularly useful for multi-storey frames taller than 3 storeys.

Approximate analysis for Vartical

SUBSTITUTE FRAME METHOD

- Analyse only a part of the frame substitute frame
- Carry out a two-cycle moment distribution



- Analysis done for:
 - Beam span moments
 - Beam support moments
 - Column moments
- Liveload positioning for the worst condition
- For the same frame, liveload positions for maximum span moments, support moments and column moments may be different
- For maximum moments at different points, liveload positions may de different









Problem 1: Total dead load is 12 kN/m. Total live kN/m. Analyse the frame for midspan positive moment on BC.

	6 m	6 m	6 m	
4 m				
	А	В	С	D
t m				
7				
				-



Distribution

factors

$$DF_{AB} = \frac{K_1}{K_1 + K_2 + K_3} = \frac{4}{4 EI/6 + 4 EI/4 + 4 EI} = 0.25 = DC$$

$$DF_{BA} = \frac{K_1}{K_1 + K_2 + K_3 + K_4} = \frac{4 EI}{4 EI/4 + 4 EI/66 + 4 EI/4 + 4 EI/66 + 4 EI/6$$

 $DF_{BC} = DF_{CD} = DF_{CB} = DF_{BA} = 0.2$

А		В	С			D	
0.25	0.2	0.2	0.2	0.2		0.25	DFs
*		*		*	<u> </u>		FE
							Μ
*		*		*			Dis
							t
*	v	*		*			CO
	*	*		*			Dist
		*					Final
		*					Momen
		*					
		*					
		*					

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Problem 2: Analyse the frame for beam negative moment at **B**. Moment of inertia of beams is 1.5 times that of columns. Total dead load is 14 kN/m and total live load is 9 kN/m.











Approvimate analysis for Harizantal

- 1. Portal method
- 2. Cantilever method
- 3. Factor method

PORTAL METHOD

Assumptions

- The points of contraflexure in all the members lie at their midpoints.
- 2. Horizontal shear taken by each interior column is double that taken by each exterior column.

Horizontal forces are assumed to act only at the joints.







 $P_1 + P_2 = Q + 2Q + 2Q + Q \qquad \Longrightarrow Q = \frac{P_1 + P_2}{6}$

Problem 3: Analyse the frame using portal



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Beam and Column





CANTH FVFP

• Frame considered as a vertical cantilever

Assumptions

- 1. The points of contraflexure in all the members lie at their midpoints.
- The direct stresses (axial stresses) in the columns are directly proportional to their distance from the centroidal vertical axis of the frame.





 $P_{1} \xrightarrow{h}_{2} \xrightarrow{m_{1}}_{M_{1}} \xrightarrow{m_{2}}_{H_{2}} \xrightarrow{m_{2}}_{H_{3}} \xrightarrow{m_{4}}_{H_{4}} B$ $V_{1} \qquad V_{2} \qquad V_{3} \qquad V_{4} \qquad V_{4} \qquad V_{4} \qquad \sum_{m} M_{B} \Rightarrow P_{1} \frac{h}{2} = V_{1} m_{1} + V_{2} m_{2} - V_{3} m_{3} - V_{4} \qquad (2)$

From (1)*and* (2), V_1, V_2, V_3, V_4 *can be found.*

 P_1 H_2 H_4 \mathbf{H}_{1} H 3 $P_1 = H_1 + H_2 + H_3 + H_4$
Problem 4: Analyse the frame using cantilever

the columns have the same area of cross section.



To locate centroidal vertical axis of the

$$\frac{1}{33} = \frac{A_1 \times 0 + A_1 \times 7 + A_1 \times 10.5 + A_1 \times 15.5}{---A_1 + A_1 + A_1 + A_1} = \frac{1}{\sqrt{3}}$$





For the top storey,

$$\sum_{m} M_{o} \Rightarrow P_{1} \frac{h}{2} = V_{1}m_{1} + V_{2}m_{2} - V_{3}m_{3} - V_{4}$$
$$\Rightarrow 120 \times \frac{3.5}{2} = V_{1} \times 15.5 + V_{4} \times 8.5 - V_{5} \times 5 - V_{4}$$







For the bottom storey,

$$\sum_{x0} M_{o} \Rightarrow 120 \times \begin{bmatrix} 3.5 \\ -3.5 \\ -2 \end{bmatrix} + 180 \times \frac{3.5}{2} = V_{1} \times 15.5 + V_{2} \times 8.5 - V_{3} \times 5 - V$$



$$\Rightarrow 120 \quad 3.5 \quad \frac{3}{52} \quad + 180 \quad \frac{3}{52} = V_1 \times 15.5 \quad 8.25 \quad 8.5 \quad 2.25V_1 \times 8.5 \quad 8.25 \quad 5$$

$$\Rightarrow V_1 = 61.267kN$$

$$V = \frac{1.25 \times 61.267}{9^{2}.283kN, 8.2} = \frac{2.25 \times 61.267}{16.709kN;^{2}} = \frac{16.709kN;^{2}}{5}$$

$$V_4 = \frac{7.25 \times 61.267}{5} = \frac{53.841kN 8.2}{5}$$

Check: $61.267 + 9.283 - 16.709 - 53.841 = 0$



Beam and Column





FACTOR

- More accurate than Portal and Cantilever methods
- Specially useful when moments of inertia of various members are different.

Basis:

- At any joint the total moment is shared by all the members in proportion to their stiffnesses
- Half the moment gets carried over to the far end

Girder and column factors:

• Relative stiffness of a

Girder factor at a joint

 $g = \frac{\sum k, of all \ columns \ meeting \ at \ the}{joint}$ $\sum k, of \ all \ members \ meeting \ at \ the}{joint}$ Column factor at a joint $k, of \ all \ members \ meeting \ at \ the}{joint} = 1 - 2$

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Moment factor for a member



where $c_m = c + half$ of column facor of far end and $g_m = g + half$ of

> $\sum C \rightarrow$ sum of column moment factors for a storey $\sum G \rightarrow$ sum of beam moment factors for a joint

Problem 5: Analyse the frame using factor



Total column moment Total column moment above ABC = 40×8.5+80×5 = 740kNm

1		2		3		4	5		6	7		8		9	10	11	11 12	
T		MEMBER		k=l/L		Σk	FACTOR		c/2, g/2 fro m	5+6		MOMEN T FACTO R		Tot al Col	Col Mo m,	DF _B =G/ΣG	Bea M o	m m c
		Col	Beam	Col	Beam		c =Σk(b e ams)/ Σ k	g =Σk(c olum n s)/Σk	far end	Cm	g _m	C= c _m k	G = g _m k	Mom, M _T	M _c = M _T × C/Σ C		= M D F	х В
		DA		0.2		0.686	0.29		0.5	0.79		0.15 8		740	99.4			
	ł		DE		0.2	0.000		0.71	0.3		1.01	0	0.202			1	122	.6
		DG		0.286			0.29		0.3	0.59		0.16 9		140	23.2			
			ED		0.2			0.59	0.36		0.95		0.19			0.59	83.2	5
E		EH		0.286		0.819	0.41		0.27	0.68		0.19 4		140	26.6			
	ļ		EF		0.133			0.59	0.4		0.99		0.132			0.41	57.8	5
		EB		0.2			0.41		0.5	0.91		0.18 2		740	114.5			
F			FE		0.133	0.772		0.79	0.3		1.09		0.145			1	13 3	.0 3
		FI		0.286			0.21		0.16	0.37		0.10 6		140	14.6			
		FC		0.2			0.21		0.5	0.71		0.14 2		740	89.3			
G		GD		0.286		0.486	0.59		0.15	0.74		0.21		140	29.1			
	╞	st	oney,	$\sum C$	-0.1	8 + 0	182+	-0.1	2,<u>5</u>3 ().23 -	+0.2	42+	026			1	29	1
			HG		0.2			0.46	0.21		0.67		0.134			0.559	16.	5
L H		HE		0.286		0.772	0.54		0.21	0.75		0.21		140	29.5			



Cummor

Approximate Methods of Analysis of Multi-storey Frames

- Analysis for vertical loads Substitute frames-Loading conditions for maximum positive and negative bending moments in beams and maximum bending moment in columns
- Analysis for lateral loads Portal method–Cantilever method– Factor method.

• Influence Line for Reaction, Moment & Shear for Indeterminate Structure

Guljit Singh CED BBSBEC, FGS. Variation of

Reaction, Shear, Moment or Deflection

at a SPECIFIC POINT

due to a **concentrated** force **moving** on member



SIGNIFICANCE

□ Influence lines are important in the design of structures that resist large **live loads**.

□ If a structure is subjected to a live or moving load, **the variation in shear and moment** is best described using influence lines.

Once the influence line is drawn, the location of the live load which will cause the greatest influence on the structure can be found very quickly

e Lines



 \Box As the car moves across the bridge, the forces in the truss members change with the position of the

car and the maximum force in each member will be at a different car location.

☐ The design of each member must be based on the maximum probable load each member will experience

☐ If a structure is to be safely designed, members must be proportioned such that the maximum force produced by dead and live loads is less than the available section capacity.

Structural analysis for variable loads consists of two steps:

1. Determining the positions of the loads at which the response function is maximum;

AND

2.Computing the maximum value of the response function.

Response Function = support reaction, axial force, shear force, or bending moment.

INFLUENCE LINE VS SFD/BMD

□ shear and moment diagrams represent the effect of fixed loads at all points along the member.

□ Influence lines represent the effect of a moving load only at a specified point on a member

TYPES OF INFLUENCE LINES

Reaction I.L.

□ Shear I.L.

Moment I.L.

Floor Girder I.L.

Truss Bar force I.L.

Structure type

□ Determinate

□ Indeterminate

Influence lines

For Determinate Structure

□ For Indeterminate Structure



Methods of constructing the shape of Influence Lines

Tabulation Method.

□ Muller –Breslau principles.

Muller-Breslau Principle

Müller-Breslau Principle: "If a function at a point on a beam, such as reaction, or shear, or moment, is allowed to act without restraint, the deflected shape of the beam, to some scale, represent the influence line of the function".



Indeterminate VS Determinate





