SYNCHRONOUS MACHINES QUESTION BANK

Ques 1. Synchronous motor for power factor correction operates at

- 1. No load with over-excited fields
- 2. No load with under-excited fields
- 3. Normal load with minimum excitation
- 4. Normal load with zero excitation

Ques 2. What happens if field winding of the synchronous motor is short circuited?

- 1. First, starts as induction motor then run as synchronous motor
- 2. Not start
- 3. Motor will burn out
- 4. Run as induction motor

Ques 3. When the field winding of an unloaded salient pole synchronous motor is open circuited the motor will

- 1. Burn
- 2. Not start
- 3. Run as induction Motor
- 4. Run as variable reluctance motor

Ques 4. The speed regulation of a synchronous motor is

- 1. 100%
- 2. 50%
- 3. 25%
- 4. 0%

Ques 5. The negative phase sequence in a three phase synchronous motor exists when the motor is

- 1. Supplied with an unbalanced voltage
- 2. Supplied with an unbalanced load
- 3. Unbalanced system fault
- 4. All of the above

Ques 6. In 3 - Φ synchronous motor if one of the phases is short circuited the motor will

- 1. Run as before
- 2. Overheated and eventually burn
- 3. Not start
- 4. Burn

Ques 7. For a synchronous motor, the breakdown torque will be proportional to

- 1. Applied voltage V
- 2. V^2
- 3. 1/V
- 4. $1/V^2$

Ques 8. In a synchronous motor, during hunting when the rotor speed exceeds the synchronous speed then damper bar develop

- 1. Induction generator torque
- 2. Harmonic
- 3. DC motor torque
- 4. Synchronous motor torque

Ques 9. In a synchronous motor, at no load condition, and with normal excitation the armature current drawn by a synchronous motor is

1. Zero

- 2. Lagging applied voltage by 90°
- 3. Leading Applied voltage by 90°
- 4. In phase with applied voltage

Ques 10. In a synchronous motor, "hunting" may be due to variation in any of the following EXCEPT

- 1. Winding friction
- 2. Frequency
- 3. Load
- 4. Supply voltage

Ques 11. For a synchronous motor, the maximum value of torque developed at an angle of

- 1. 120 degree
- 2. 45 degree
- 3. 0 degree
- 4. 90 degree

Ques 12. What happens to the synchronous motor when the excitation of an unloaded salient-pole synchronous motor suddenly gets disconnected?

- 1. Run as variable reluctance motor
- 2. Run as induction motor
- 3. Motor will stop
- 4. None of the above

Ques 13.A synchronous motor working at leading power factor can be used as

- 1. Synchronous induction motor
- 2. Static condenser
- 3. Synchronous condenser
- 4. None of the above

Ques 14. Which of the following motor is not self-starting?

- 1. Wound rotor induction motor
- 2. Squirrel cage induction motor
- 3. DC series motor
- 4. Synchronous motor

Ques 15. Which of the following motor can operate on lagging as well as leading power factor?

- 1. DC series motor
- 2. Wound rotor induction motor
- 3. Squirrel cage induction motor
- 4. Synchronous motor

Ques 16. A synchronous motor is switched on to supply with its field windings short circuited. It will run as

- 1. DC series motor
- 2. Induction motor
- 3. Induction motor then run as synchronous motor
- 4. None of the above

Ques 17. The back emf in the stator of a synchronous motor depends on

- 1. Flux density
- 2. DC excitation
- 3. Load on the motor
- 4. Speed of the rotor

Ques 18. The main reason of embedding the damper winding in the pole face is to

- 1. Eliminate losses on account of air friction
- 2. Reduce bearing friction

- 3. Eliminate hunting and provide starting torque
- 4. Eliminate air friction

Ques 19. A 3 phase, salient pole synchronous motor is fed from an infinite bus and is running at no load. Now if the field current of the motor is reduced to zero then the

- 1. Motor will run at synchronous speed
- 2. Motor will stop
- 3. Motor will run at low speed
- 4. Motor will burn

Ques 20. The maximum value of torque that a synchronous motor, can develop without losing its synchronism, is known as

- 1. Pull out torque
- 2. Breaking torque
- 3. Slip torque
- 4. Non-synchronizing torque

Ques 21. What is the ratio of no load speed to full load speed of a 200 kVA, 12 poles, 2200 V, 3 phase, 60 Hz synchronous motor?

- 1. Infinite
- 2. 1
- 3. 1.1
- 4. 1.21

Ques 22. In case of synchronous motor if the back emf generated in the armature at no load is approximately equal to the applied voltage, then the

- 1. Torque generated is maximum
- 2. Motor is fully loaded
- 3. Excitation is 100%

4. No Excitation at all

Ques 23. The armature current of the synchronous motor has large values for

- 1. High excitation
- 2. Low excitation
- 3. Both high and low excitation
- 4. None of the above

Ques 24. The construction of a synchronous motor resembles which of the following machine

- 1. Differential compound motor
- 2. Alternator
- 3. Dc series motor
- 4. Induction motor

Ques 25. The synchronous motors are not self-starting because

- 1. The direction of torque on the rotor reverses after every half cycle.
- 2. Slip is not present in synchronous machine
- 3. Starting winding is not present in synchronous machine
- 4. DC excitation is used

Ques 26. If a synchronous motor fails to pull into synchronism after applying dc field current, the main cause is

- 1. Low short circuit ratio
- 2. High field current
- 3. High core losses
- 4. Low field current

Ques 27. What happens when a synchronous motor is connected to an infinite bus while operating on leading power factor?

- 1. Excitation voltage will be independent of the supply voltage.
- 2. Excitation voltage will be more than the supply voltage.
- 3. Excitation voltage will be less than the supply voltage.
- 4. Excitation voltage will be equal to the supply voltage.

Ques 28. Which of the following losses is not dissipated by the stator core surface in a synchronous motor?

- 1. Eddy current losses in the conductors
- 2. Iron losses in the stator
- 3. Windage losses.
- 4. Copper losses in the slot portion of the conductors

Ques 29. The direction of rotation of synchronous motor can be reversed by reversing

- 1. Field winding
- 2. Polarity of the rotor poles
- 3. Supply phase sequence
- 4. None of the above

Ques 30. In synchronous motor out of the following losses, which one will have the highest proportion?

- 1. Stator copper losses
- 2. Iron losses
- 3. Eddy current losses
- 4. Friction and windage losses

Ques 31. The speed of a synchronous motor

- 1. Increases as load increases
- 2. Adjusts itself to new equilibrium speed whenever load changes.
- 3. Always remains constant

4. Reduces as load increases

Ques 32. In a synchronous motor if the saturation is neglected, then the short circuit ratio (SCR) will be related to the synchronous reactance (xd) as

- 1. SCR = 1/(xd)
- 2. $SCR = 1/(xd)^2$
- 3. SCR = xd
- 4. $SCR = (xd)^2$

Ques 33. Which of the following devices can be used as a phase advancer?

- 1. Synchronous motor working at lagging power factor
- 2. Synchronous motor working at leading power factor
- 3. Squirrel cage induction motor
- 4. Slip ring induction motor

Ques 34. In a synchronous machine is called as doubly excited machine because

- 1. It can be over excited
- 2. It needs twice the normal exciting current
- 3. It has two sets of rotor poles
- 4. Both its rotor and stator are excited

Ques 35. In case of a 3 phase synchronous motor, percentage of maximum speed variation is

- 1. 5%
- 2. Zero
- 3. 10%
- 4. 3%

Ques 36. If the field of a synchronous motor is under excited, the power factor will be

- 1. Lagging
- 2. Leading
- 3. Zero
- 4. None of the above

Ques 37. Which of the following is an unexcited single phase synchronous motor?

- 1. Reluctance motor
- 2. Repulsion motor
- 3. A.C. series motor
- 4. Universal motor

Ques 38. The damper winding in a synchronous motor is provided for

- 1. Starting torque only
- 2. Reduce eddy currents
- 3. Prevent hunting and provide the starting torque.
- 4. Reduce the noise level

Ques 39. When the field of a synchronous motor is over excited, the power factor will be

- 1. Leading
- 2. Lagging
- 3. Zero
- 4. Unity

Ques 40. A Synchronous motor can operate at

- 1. Unity power factor
- 2. Leading power factor
- 3. Lagging power factor
- 4. Leading as well as lagging power factor