

Digital Electronics Question Bank - (4th Sem EE)

Unit 1: Number Systems and Boolean algebra

1. Convert $(234.625)_{10}$ to binary.
2. Convert $(10111.011)_2$ to decimal.
3. Convert $(5A2.B)_{16}$ to octal.
4. Convert $(673.4)_8$ to hexadecimal.
5. Perform binary addition: $11101 + 10111$.
6. Perform binary subtraction: $11001 - 10110$.
7. Perform binary multiplication: $1101 * 1111$
8. Perform binary division: $111100 \div 110$.
9. Find the 2's complement of 101101_2
10. Subtract (1010) from (1101) using 2's complement.
11. Convert $(42)_{10}$ to Gray code.
12. Convert Gray code (11010) to binary.
13. State and prove the distributive laws of Boolean algebra.
14. Simplify: $AB + A'C + BC$ given $AB + C = 1$.
15. Simplify: $(A + B)(A' + C)(B + C)$.
16. Implement $F(A, B, C) = A'B + AC'$ using NAND gates only.
17. Implement $F(A, B, C) = (A + B')C$ using NOR gates only.
18. Draw the truth table for a 3-input XOR gate.
19. Explain the concept of Boolean duality.
20. Show how a XOR gate can be made from basic logic gates.
21. Perform the following conversions:

(a) $(3A.2F)_{16}$ to binary

(b) $(573)_8$ to decimal

(c) $(11011.011)_2$ to octal

(d) $(245)_{10}$ to Excess-3 code

22. Perform the following 2's complement arithmetic:

(a) $011010 + 101011$

(b) $110010 - 011101$

(c) Interpret the results, including overflow conditions.

23. Explain the application of Gray codes in digital systems, particularly in rotary encoders.

24. Design a BCD adder to add two BCD numbers and produce a BCD sum.

25. What is the Hamming code? Explain how it is used for error detection and correction.

26. Explain the difference between weighted and non-weighted codes with examples.

Unit 2: Combinational Logic Circuits

1. Minimize $F(A, B, C, D) = \sum m(0, 1, 4, 5, 9, 11, 12, 15)$ using a K-map.

2. Minimize $F(A, B, C, D) = \pi M(0, 2, 5, 8, 10, 13, 14)$ using a K-map.

3. Use the Quine-McCluskey method to simplify $F(A, B, C, D) = \sum m(0, 1, 3, 7, 8, 9, 11, 15)$.

4. Design a half-subtractor.

5. Design a full-subtractor using two half-subtractors and an OR gate.

6. Design a 4-bit adder-subtractor circuit.

7. Implement a 8-to-1 multiplexer using 4-to-1 multiplexers.

8. Implement a 1-to-16 demultiplexer using 1-to-4 demultiplexers.

9. Design a BCD to Excess-3 code converter.

10. Design a 2-bit magnitude comparator.
11. Explain the working of a parity generator and checker.
12. Design a circuit that detects the binary sequence 1001.
13. Design a decimal to BCD encoder.
14. Design a 4 to 2 encoder.
15. Explain how to expand a decoder.
16. Design a circuit to implement the boolean function, $F=AB + CD$ with the use of gates.
17. Explain the concept of hazards in combinational circuits.
18. Simplify the Boolean expression using Karnaugh maps and implement it using NAND gates:

$$F(A,B,C,D)=\sum m(1,3,5,7,9,11,13,15)$$

19. Simplify the Boolean expression using Quine-McCluskey method:

$$F(A,B,C,D)=\sum m(0,1,3,7,8,9,11,15)$$

20. Implement the following function using a multiplexer:

$$F(A,B,C)=\sum m(1,3,5,6)$$

21. Explain the concept of positive and negative logic.
22. Prove the following Boolean identities:

$$(a) A+AB=A+B$$

$$(b) AB+AC+BC=AB+AC$$

23. Design a 4-bit magnitude comparator.
24. Design a BCD-to-binary converter.
25. Design a code converter to convert from Excess-3 to BCD.
26. Describe the operation of a carry-lookahead adder and its advantages.

Unit 3: Sequential Logic Circuits

1. Definitions:

- a. Define a sequential circuit. How does it differ from a combinational circuit?
- b. Explain the concept of "state" in a sequential circuit.
- c. What is the role of a clock signal in synchronous sequential circuits?

2. Latches and Flip-Flops:

- a. Explain the operation of an SR latch. What are its limitations?
- b. Describe the working principle of a D flip-flop.
- c. Compare and contrast JK and T flip-flops.
- d. Explain the concept of a master-slave flip-flop and its purpose.
- e. Differentiate between level-triggered and edge-triggered flip-flops.

3. State Diagrams and State Tables:

- a. What is a state diagram? How is it used to represent the behavior of a sequential circuit?
- b. What is a state table? How is it related to a state diagram?
- c. Explain the process of converting a state diagram to a state table.

4. Counters:

- a. Explain the difference between synchronous and asynchronous counters.
- b. Design a modulo-N counter using flip-flops.
- c. Describe the operation of a ring counter and a Johnson counter.
- d. What are the uses of counters in digital systems?

5. Shift Registers

- a. Explain the operation of different types of shift registers (SISO, SIPO, PISO, PIPO).
- b. What are the applications of shift registers?

6. Explain the difference between level-triggered and edge-triggered flip-flops.

7. Draw the timing diagram for a JK flip-flop.

8. Convert a D flip-flop to a T flip-flop.
9. Design a 4-bit parallel-in serial-out (PISO) shift register.
10. Design a 4-bit serial-in parallel-out (SIPO) shift register.
11. Design a modulo-10 synchronous counter.
12. Design a 3-bit asynchronous up/down counter.
13. Explain the operation of a twisted ring counter.
14. Draw the state diagram for a modulo-6 counter.
15. Explain the difference between synchronous and asynchronous sequential circuits.
16. Design a sequential circuit to implement a given state table.
17. Explain the concept of propagation delay.
18. Explain the difference between synchronous and ripple counters.

Unit 4 Analog to Digital and Digital to Analog Converters

1. Define Analog-to-Digital (A/D) and Digital-to-Analog (D/A) conversion.
2. Explain the importance of A/D and D/A converters in digital systems.
3. List and define the key parameters of A/D and D/A converters (resolution, accuracy, linearity, settling time, conversion time, etc.).
4. Differentiate between resolution and accuracy in A/D and D/A converters.
5. Explain the concept of quantization error and how it affects the accuracy of A/D conversion.
6. Explain the concept of sampling theorem.
7. What is aliasing, and how can it be prevented in A/D conversion?
8. Explain the purpose of a sample-and-hold circuit in A/D conversion.
9. Describe the advantages and disadvantages of different A/D and D/A converter types.

10. What is the impact of temperature on the performance of A/D and D/A converters?
11. What are the common applications of A/D and D/A converters in real-world systems?
12. Explain the concept of successive approximation in the context of A/D converters.

D/A Converter Types:

1. Explain the working principle of a binary-weighted resistor D/A converter.
2. Describe the advantages and disadvantages of a binary-weighted resistor D/A converter.
3. Explain the working principle of an R-2R ladder D/A converter.
4. Describe the advantages and disadvantages of an R-2R ladder D/A converter.
5. Compare and contrast binary-weighted resistor and R-2R ladder D/A converters.

A/D Converter Types:

1. Explain the working principle of a flash A/D converter.
2. Describe the advantages and disadvantages of a flash A/D converter.
3. Explain the working principle of a successive approximation A/D converter.
4. Describe the advantages and disadvantages of a successive approximation A/D converter.
5. Explain the working principle of a dual-slope A/D converter.
6. Describe the advantages and disadvantages of a dual-slope A/D converter.
7. Compare and contrast flash, successive approximation, and dual-slope A/D converters.
8. What is the difference between a SAR ADC and a flash ADC?